# Package 'cxhull'

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<b>Description</b> Computes the convex hull in arbitrary dimension, based on the Qhull library ( <a href="http://www.qhull.org">http://www.qhull.org</a> ). The package provides a complete description of the convex hull: edges, ridges, facets, adjacencies. Triangulation is optional.
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<pre>URL https://github.com/stla/cxhull</pre>
BugReports https://github.com/stla/cxhull/issues
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cxhull

Convex hull

# Description

Computes the convex hull of a set of points.

# Usage

```
cxhull(points, triangulate = FALSE)
```

# Arguments

points numeric matrix, one point per row triangulate logical, whether to triangulate the convex hull

#### Value

A list providing a lot of information about the convex hull. See the **README** file for details.

```
library(cxhull)
points <- rbind(
    c(0.5,0.5,0.5),
    c(0,0,0),
    c(0,0,1),
    c(0,1,0),
    c(0,1,1),
    c(1,0,0),
    c(1,0,1),
    c(1,1,0),
    c(1,1,1)
)
cxhull(points)
```

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#### **Description**

Computes the vertices and the edges of the convex hull of a set of points.

#### Usage

```
cxhullEdges(points, adjacencies = FALSE, orderEdges = FALSE)
```

#### **Arguments**

points	numeric matrix, one point per row; it must contain at least three columns (the two-dimensional case is not implemented yet)
adjacencies	Boolean, whether to return the vertex adjacencies
orderEdges	Boolean, whether to order the edges in the output

#### Value

A list with two fields: vertices and edges. The vertices field is a list which provides an id for each vertex and its coordinates. If adjacencies=TRUE, it provides in addition the ids of the adjacent vertices for each vertex. The edges fields is an integer matrix with two columns. Each row provides the two ids of the vertices of the corresponding edge.

```
library(cxhull)
# let's try with the hexacosichoron (see `?hexacosichoron`)
   it is convex so its convex hull is itself
VE <- cxhullEdges(hexacosichoron)</pre>
edges <- VE[["edges"]]
random_edge <- edges[sample.int(720L, 1L), ]</pre>
A <- hexacosichoron[random_edge[1L], ]
B <- hexacosichoron[random_edge[2L], ]</pre>
sqrt(c(crossprod(A - B))) # this is 2/phi
# Now let's project the polytope to the H4 Coxeter plane
phi <- (1 + sqrt(5)) / 2
u1 <- c(
  0,
  2*phi*sin(pi/30),
  0,
  1
)
u2 <- c(
  2*phi*sin(pi/15),
  2*sin(2*pi/15),
```

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```
0
)
u1 <- u1 / sqrt(c(crossprod(u1)))</pre>
u2 <- u2 / sqrt(c(crossprod(u2)))</pre>
# projections to the Coxeter plane
proj <- function(v){</pre>
          c(c(crossprod(v, u1)), c(crossprod(v, u2)))
points <- t(apply(hexacosichoron, 1L, proj))</pre>
# we will assign a color to each edge
                    according to the norms of its two vertices % \left( 1\right) =\left( 1\right) \left( 
norms2 <- round(apply(points, 1L, crossprod), 1L)</pre>
 ( tbl <- table(norms2) )</pre>
 #> 0.4 1.6 2.4 3.6
#> 30 30 30 30
values <- as.numeric(names(tbl))</pre>
grd <- as.matrix(expand.grid(values, values))</pre>
grd <- grd[grd[, 1L] <= grd[, 2L], ]</pre>
pairs <- apply(grd, 1L, paste0, collapse = "-")</pre>
colors <- hcl.colors(nrow(grd), palette = "Hawaii", rev = TRUE)</pre>
if(require("colorspace")) {
          colors <- colorspace::darken(colors, amount = 0.3)</pre>
}
names(colors) <- pairs</pre>
# plot ####
opar <- par(mar = c(0, 0, 0, 0))
plot(
          points[!duplicated(points), ], pch = 19, cex = 0.3, asp = 1,
          axes = FALSE, xlab = NA, ylab = NA
)
for(i in 1L:nrow(edges)){
          twopoints <- points[edges[i, ], ]</pre>
          nrms2 <- round(sort(apply(twopoints, 1L, crossprod)), 1L)</pre>
          pair <- paste0(nrms2, collapse = "-")</pre>
          lines(twopoints, lwd = 0.5, col = colors[pair])
}
par(opar)
```

daVinciSphere

Leonardo da Vinci's 72-sided sphere

#### **Description**

A matrix giving the 62 vertices of da Vinci's 72-sided sphere, a convex polyhedra with 72 faces.

# Usage

daVinciSphere

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#### **Format**

A matrix with 62 rows and 3 columns.

#### **Source**

http://www.matematicasvisuales.com/english/html/geometry/space/sphereCampanus.html

dihedralAngles

Dihedral angles

# **Description**

Dihedral angles of a convex hull.

# Usage

```
dihedralAngles(hull)
```

# **Arguments**

hull

an output of cxhull applied to 3D points

#### Value

A dataframe with three columns. The two first columns represent the edges, given as a pair of vertex indices. The third column provides the dihedral angle in degrees corresponding to the edge, that is the angle between the two faces incident to this edge. This is useful to find edges between two coplanar faces: if the faces are exactly coplanar then the dihedral angle is 180, but because of numerical approximation one can consider that there is coplanarity when the dihedral angle is greater than 179, for example. This function is used in plotConvexHull3d to get rid of such edges (if the user sets a value to the argument angleThreshold).

```
# a cube ####
library(cxhull)
points <- rbind(
    c(0.5,0.5,0.5),
    c(0,0,0),
    c(0,1,0),
    c(0,1,1),
    c(1,0,0),
    c(1,1,1)
)
hull <- cxhull(points)
dihedralAngles(hull)</pre>
```

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EdgesAB

Edges of a triangulated 3D convex hull

# Description

Edges of a triangulated 3D convex hull given by the ids of the vertices in a matrix, plus a column indicating the border edges.

#### Usage

```
EdgesAB(hull)
```

# **Arguments**

hull

an output of cxhull applied to 3D points and with the option triangulate=TRUE

#### Value

A character matrix with three columns. Each row provides the ids of the two vertices of an edge, and a yes/no indicator of whether the edge is a border edge.

```
library(cxhull)
library(rgl)
dodecahedron <- t(dodecahedron3d()$vb[-4L, ])
hull <- cxhull(dodecahedron, triangulate = TRUE)
triangles <- TrianglesXYZ(hull)
triangles3d(triangles, color = "yellow")
edges <- EdgesAB(hull)
trueEdges <- edges[edges[, 3L] == "yes", c(1L, 2L)]
otherEdges <- edges[edges[, 3L] == "no", c(1L, 2L)]
vertices <- VerticesXYZ(hull)
for(i in 1:nrow(trueEdges)){
  lines3d(vertices[trueEdges[i, ], ], color = "blue", lwd = 3)
}
for(i in 1:nrow(otherEdges)){
  lines3d(vertices[otherEdges[i, ], ], color = "red", lwd = 3)
}</pre>
```

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EdgesXYZ

Edges coordinates

#### **Description**

The coordinates of the extremities of the edges in a matrix, plus a column indicating which edges are border edges.

#### Usage

EdgesXYZ(hull)

#### **Arguments**

hull

an output of cxhull applied to 3D points and with the option triangulate=TRUE

#### Value

A numeric matrix with four columns. The first three values of a row are the coordinates of a vertex at the extremity of an edge, and the fourth column indicates whether the edge is a border edge.

hexacosichoron

Vertices of the 600-cell

#### **Description**

A matrix giving the 120 vertices of the hexacosichoron, a regular convex 4D polytope also known as the "600-cell", with edge length 2/phi, where phi is the golden number. It has 720 edges.

# Usage

hexacosichoron

# **Format**

A matrix with 120 rows and 4 columns.

#### **Source**

https://www.qfbox.info/4d/600-cell

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Mesh of a 3d convex hull

#### **Description**

Extract the vertices and the faces from a 3d convex hull.

#### Usage

```
hullMesh(hull, simplify = TRUE, rgl = FALSE)
```

#### **Arguments**

hull a 3d convex hull, output of cxhull

simplify Boolean, whether to return the faces as a matrix instead of a list if possible, i.e.

if all faces have the same number of edges; this argument is possibly ignored if

rgl=TRUE, see below

rgl Boolean, whether to return a **rgl** mesh (class mesh3d) if possible, i.e. if each face

has three or four edges; if TRUE and the rgl mesh is possible, then the simplify

argument has no effect

#### Value

A list giving the vertices and the faces, or a **rgl** mesh.

# Note

Unless all faces are triangular, the output does not define a mesh with coherently oriented faces.

```
library(cxhull)
hull <- cxhull(daVinciSphere)
septuaginta <- hullMesh(hull, rgl = TRUE)
library(rgl)
open3d(windowRect = c(50, 50, 562, 562))
shade3d(septuaginta, color = "darkred")
# some quad faces are misoriented:
open3d(windowRect = c(50, 50, 562, 562))
shade3d(septuaginta, color = "tomato", back = "culled")</pre>
```

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hullSummary

Summary of 3D convex hull

# Description

Summary of a triangulated 3D convex hull

# Usage

```
hullSummary(hull)
```

# Arguments

hull

an output of cxhull applied to 3D points and with the option triangulate=TRUE

#### Value

A list with the vertices and the facets.

#### **Examples**

```
library(cxhull)
# pyramid
pts <- rbind(
    c(0, 0, 0),
    c(1, 0, 0),
    c(1, 1, 0),
    c(0.5, 0.5, 1),
    c(0.5, 0.5, 0.9),
    c(0, 1, 0)
)
hull <- cxhull(pts, triangulate = TRUE)
hullSummary(hull)</pre>
```

plotConvexHull3d

Plot triangulated 3d convex hull

# Description

Plot a triangulated 3d convex hull with rgl.

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#### Usage

```
plotConvexHull3d(
  hull,
  angleThreshold = NULL,
  edgesAsTubes = TRUE,
  verticesAsSpheres = TRUE,
  palette = NULL,
  bias = 1,
  interpolate = "linear",
  g = identity,
  facesColor = "navy",
  edgesColor = "gold",
  tubesRadius = 0.03,
  spheresRadius = 0.05,
  spheresColor = edgesColor,
  alpha = 1
)
```

#### Arguments

hull an output of cxhull applied to 3d points and with the option triangulate=TRUE

angleThreshold a threshold angle in degrees, typically 179, to get rid of edges between coplanar

faces: edges whose corresponding dihedral angle is greater than this threshold

are removed; NULL to use another method (see the Leonardo example)

edgesAsTubes Boolean, whether to draw the edges as tubes

verticesAsSpheres

Boolean, whether to draw the vertices as spheres

palette a vector of colors to make a color gradient for the faces; if NULL, the colors of

the faces are controlled by the facesColor argument

bias, interpolate

if palette is not NULL, these arguments are passed to colorRamp

g a function defined on [0, 1] and taking its values in [0, 1]; it is composed with

the function created by colorRamp, based on palette

facesColor the color(s) for the faces; this argument is ignored if the argument palette is

not NULL; otherwise there are three possibilities for facesColor: a single color, a vector of colors with length the number of triangles, in which case one color is assigned per triangle, or a vector of colors with length the number of faces, after merging the triangles, in which case one color is assigned per face; use

hullSummary to know the number of faces

edgesColor the color for the edges

tubesRadius the radius of the tubes when edgesAsTubes=TRUE

spheresRadius the radius of the spheres when verticesAsSpheres=TRUE spheresColor the color of the spheres when verticesAsSpheres=TRUE number between 0 and 1 controlling the opacity of the faces

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#### Value

No value.

#### **Examples**

```
library(cxhull)
library(rgl)
cuboctahedron <- t(cuboctahedron3d()$vb[-4L, ])</pre>
hull <- cxhull(cuboctahedron, triangulate = TRUE)</pre>
# single color ####
open3d(windowRect = c(50, 50, 562, 562))
plotConvexHull3d(hull)
# gradient ####
open3d(windowRect = c(50, 50, 562, 562))
if(getRversion() < "4.1.0"){}
  palette <- "Viridis"</pre>
}else{
  palette <- "Rocket"
plotConvexHull3d(hull, palette = hcl.colors(256, palette), bias = 0.5)
library(cxhull)
library(rgl)
# Leonardo da Vinci's 72-sided sphere ####
hull <- cxhull(daVinciSphere, triangulate = TRUE)</pre>
# there are some undesirable edges:
plotConvexHull3d(
  hull, tubesRadius = 0.07, spheresRadius = 0.1
# => use `angleThreshold` to get rid of these edges:
plotConvexHull3d(
  hull, angleThreshold = 179,
  tubesRadius = 0.07, spheresRadius = 0.1
)
```

TrianglesXYZ

Triangles of a triangulated 3D convex hull

#### **Description**

Coordinates of the vertices of the triangles of a triangulated 3D convex hull.

# Usage

```
TrianglesXYZ(hull)
```

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#### **Arguments**

hull

an output of cxhull applied to 3D points and with the option triangulate=TRUE

#### Value

A matrix with three columns. Each row represents the coordinates of a vertex of a triangle.

# **Examples**

```
library(cxhull)
library(rgl)
dodecahedron <- t(dodecahedron3d()$vb[-4L, ])
hull <- cxhull(dodecahedron, triangulate = TRUE)
triangles <- TrianglesXYZ(hull)
triangles3d(triangles, color = "firebrick")</pre>
```

VerticesXYZ

Convex hull vertices

# Description

The coordinates of the vertices of a 3D convex hull.

#### Usage

```
VerticesXYZ(hull)
```

# Arguments

hull

an output of cxhull applied to 3D points

#### Value

A matrix with three columns. Each row represents the coordinates of a vertex and the row names are the ids of the vertices.

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